College of Engineering Department of **Mechanical & Industrial Engineering**

Objective

College of Engineering School of Electrical Engineering & Computer Science

To Predict ► To Design ► To Perform

ME, ECE Capstone Design Programs

Project 34: Crush Prevention Tommy Brocato [EE], James Cardinal [EE], Stephen Colomb [ME], David DeGeneres [ME], Jonathan Gioe [ME], Alejandro Leyton [ME], Zachary Roberts [ECE], Rodrigo



Stopping Distance

Measurable Specifications Speed



Sponsors: Tony Brouillette

Advisors: Dr. Devireddy, Dr. Choi, Matthew

Goals vs Results

Category	Goal	Actual
Budget	\$10,000	\$6,370
Ultrasonic sensor sensing distance	2.5 m	4.25 m
LIDAR sensor sensing distance	2.3 m	20 m
Stopping distance when booming	13.8 in	13.6 in
Stopping distance when driving	20 in	4.75 in
Number of cycles in air tank	250 strokes	122 strokes
Speaker loudness	≥ 110 dB	
Housing robustness	4 J	170 J
Turn down speed dial to creep	312°	312°

System Upgrades

- Integrate sensor housing to basket
- No need for brackets or mounting hardware
- Truly modular design
- Improved LIDAR sensors
- Quanergy producing solid state 3D sensors late 2018



Rodriguez [ME] **Corrective Action System**

Travel Mode

			when E-stop engaged	
	Creep Mode	Rabbit Mode	Creep Mode	Rabbit Mode
oming In and Out	$.1\frac{ft}{s}$	$.7 \frac{ft}{s}$	1 in	1 in
om Articulating	$.04 \frac{rad}{s}$	$.5 \frac{rad}{s}$	5 in	5 in
ive	2.76 $\frac{ft}{s}$	$6.8 \frac{ft}{s}$	9 in	4.5 ft