College of Engineering Department of **Mechanical & Industrial Engineering** 

College of Engineering School of Electrical Engineering & Computer Science

# To Predict ► To Design ► To Perform

# **ME, ECE Capstone Design Programs**



LSU

# Team 24: NASA Human Exploration Rover Challenge

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# Jack Rettig ExconMobil 35 SOLIDWORKS

### Background

Student competition at NASA in Huntsville, Alabama on April 12-14, 2018.

- · Design, build, test, and race human powered rovers on simulated planetary terrain course.
- Win points by completing obstacles and tasks.



### **Objective Statement**

Design, manufacture, and test a robust human powered vehicle using fundamental and advanced engineering practices to complete the NASA competition mission objectives, in order to gain points and place first.

## **Engineering Specifications**

Specification	Target	Actual
Maximum Speed	≥10 MPH	$\checkmark$
Turn Radius	≤ 15 ft	$\checkmark$
Vehicle Weight	< 170 lbs	×
Width	≤ 5 ft.	$\checkmark$
Fender Area	$\geq$ 120 in <sup>2</sup>	$\checkmark$
Collapsed Dimensions	≤5x5x5 ft³	$\checkmark$
Driver Clearance	$\geq$ 15 in. from grade	$\checkmark$

Concept Selection

Oct 3 – Oct 18

Concept Generation

Sep 19 - Oct 2

# Sponsors: Jack Rettig represented by Dr. Dimitris Nikitopoulos

# **CAD Model Versus Actual Prototype**



## Main Component Analysis

#### Frame

#### Loads Applied:

- 1500 lb. impact load
- 375 lb. at upper supports from suspension Fixed at seat supports

### Results:

- Max Stress: 27.7 ksi seat supports
- · Yield Strength of 6061-T6 Aluminum: 40 ksi Factor of Safety: 1.44

### Wheel

Loads Applied: 1500 lb. impact between spokes

#### Results:

- · Since tetrahedrals are unreliable, results were only used qualitatively
- · Max Stress: above yield at curve of supports · Increased the thickness of the spokes at this location



Testing

# **Testing Plans**

Vehicle Turn Radius - Rover must be able to turn within the constraint in order to progress through the course Vehicle Stability - Steep inclines/rough terrain require rover to be stable with a well-positioned center of mass Vehicle Speed - Find the top vehicle speed and time to get there to accurately predict course time Proficiency - Rover needs to allow drivers to complete tasks,

as well as obstacles Dye Penetrant/Fillet Weld Bend Test - Examine weld fusion and porosity of welded Aluminum

### Budget



# Manufacturing

Water jet - Frame bracing, crankset supports, wheel spokes

CNC mill - Wheel hubs, connecting yokes, etc. CNC lathe - Suspension and frame connections Wire EDM - Control arm connectors Manual lathe - Shafts, collars, rear frame connectors

End mill - Rear wheel hubs, various frame components, boring/drilling

TIG and MIG welding - Aluminum and carbon steel

Engineering Analysis Purchasing Dec 1 – Mar 31 Oct 19 - Nov 30

Manufacturing/Assembly Dec 15 – Apr 1

Apr 1 – Ap<u>r 11</u>

April 12-14, 2018