College of Engineering Department of **Mechanical & Industrial Engineering**

College of Engineering School of Electrical Engineering & Computer Science

To Predict ► To Design ► To Perform

ME, ECE Capstone Design Programs

User Interface and Pedal Board

Robotic Guitar Interface Device-Rehabilitation and Research Guitar Bot (RRGB Team #1 - Zachary Brandon, Michael Bryant, Alexander Douglas, Matthew Haase, Kevin Justice, James Kirsch, and Nicholas Miller

School of Kinesiology

PEDAL 3

PEDAL 4

RUN

Objective Statement

The RRGB will be designed primarily as a research apparatus for the Louisiana State University Kinesiology Department that will enable stroke victims to undergo an experimental rehabilitation technique that combines rhythmic and discrete movements while playing guitar.

Engineering Specifications

Functions:

- Actuates chords on first four frets of guitar
- Foot pedal controls
- Computer-Based user interface for device configuration
- Scrolling Timing Indicator on Computer Interface

Constraints/Measurable Specifications:

- Attachable/Detachable
- PC compatible user interface
- Two modes of operation
- Four foot pedals
- Less than 500ms actuation
- delav

Electronic Hardware Schematic





Side view of fretting device without enclosure (Forms chord shapes)



Back view of fretting device (left). Power supply along with pedals and pedal board (right).

Safety Considerations

Moving and electrical components will be enclosed to prevent injury

January

GUI Coding

Construction

Device

 All electronics will be capable of handling currents that meet or exceed the range required for normal operation of the device.

December

Report

Prototype Final

Part Purchasing



Four Pedal Mode page from the User Interface.



Device pedal hardware (Controls Actuation of Chords)

Budget



Sponsors: Dr. Nikita Kuznetsov and Dr. Hunter Gilbert

Adviser: Dr. Jerry Trahan

February